

2020





A project by





Next generation fresh fish picking system and special quality control

Sustainable Production

Digitalization

Human-Machine Collaboration

Robotics

Project consortium











Pick-a-Future provides a Human-Robot Collaboration solution for a quality checking and picking process for retail manufacturing. It combines practical challenges that are tackled by several technical innovations.

The Al-based robot picking system uses 3D scan and localisation combined with a new gripper that was developed to handle flexible and slippery goods without damaging them.

Moreover, the system uses optical hyperspectral imaging in the near-infrared region, which enables the identification of organic molecules via absorption spectroscopy for quality control.

The overall integration aims to be used in the food industry and focuses on fish manipulation and inspection of diverse sizes, shapes, appearance, and deformability of the handled goods. Food industry companies are welcome to scale up the solution in possible post-projects.







