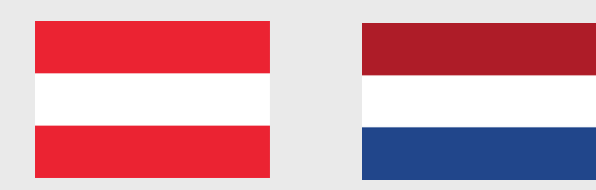


CoCoA5

2024



A project by



Collaborating and coupled AGV swarms with extended environment recognition

Project consortium

AVG

Automotive sector



Autonomous swarm fleet control



Summary

The project is aimed at bringing a new AGV based internal transport system. It is created on the foundation of substantial manufacturing know-how of Magna with collaboration of charismaTec.

It exceeds the current state of the art with unique brownfield activity and an unusually high max load. Single use cases and additional implementation of swarm intelligence features in this project should prepare Market Entry.

